

# STATISTICS FOR DATA ANALYSIS

EMPHASIS: METHODS THAT ARE INSENSITIVE TO  
HOW DATA OR ERRORS ARE DISTRIBUTED.

## I. FITTING

- LINEAR LEAST SQUARES (ADVANTAGES & LIMITATIONS)
- MINIMUM ABSOLUTE DEVIATION; NONLINEAR FITTING  
(LATER WILL TOUCH ON A NONPARAMETRIC ALTERNATIVE)

## II. CONFIDENCE INTERVALS

- $\chi^2$  (BRIEFLY)
- STATISTICAL BOOTSTRAP
- INSTRUMENT FOCUS TEST EXAMPLE (FITTING W/UNKNOWN ERRORS)

Today

## III. NONPARAMETRIC (DISTRIBUTION FREE) METHODS

- EXAMPLE: MEDIAN VS. MEAN
- MEASURES OF CORRELATION
- NONPARAMETRIC FITTING
- KOLMOGOROV-SMIRNOV TEST
- EXAMPLE: DISTRIBUTION OF NEARBY STARS

WE TAKE K-S TEST AS AN EXAMPLE OF  
FREQUENTIST HYPOTHESIS TESTING.

examples/Octave/statistical\_analysis/descriptive\_stats\_examples/  
gauss\_example.m & lorentzian\_example.m

①

## CORRELATION

A SUBSET OF STATISTICAL DEPENDENCE; APPLIES ONLY TO ORDINAL OR CONTINUOUS VARIABLES

GIVEN  $\{x_1 \dots x_n\}$  AND  $\{y_1 \dots y_n\}$

CORRELATION MEANS A MONOTONIC TREND IN  $y$  vs.  $x$



LINEAR CORRELATION COEFFICIENT:

$$r = \frac{\sum_i (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_i (x_i - \bar{x})^2} \sqrt{\sum_i (y_i - \bar{y})^2}}$$

NORMALIZATION  
STUFF

$r$  ASKS: WHEN  $x_i > \bar{x}$ , IS  $y_i > \bar{y}$  ? {

WHEN  $x_i < \bar{x}$ , IS  $y_i < \bar{y}$  ? }

IF  $y = mx + b$  EXACTLY,

$$r = \begin{cases} 1 & m > 0 \\ -1 & m < 0 \end{cases}$$

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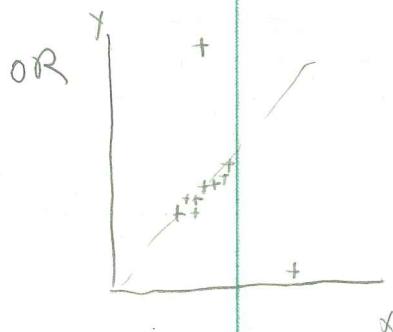
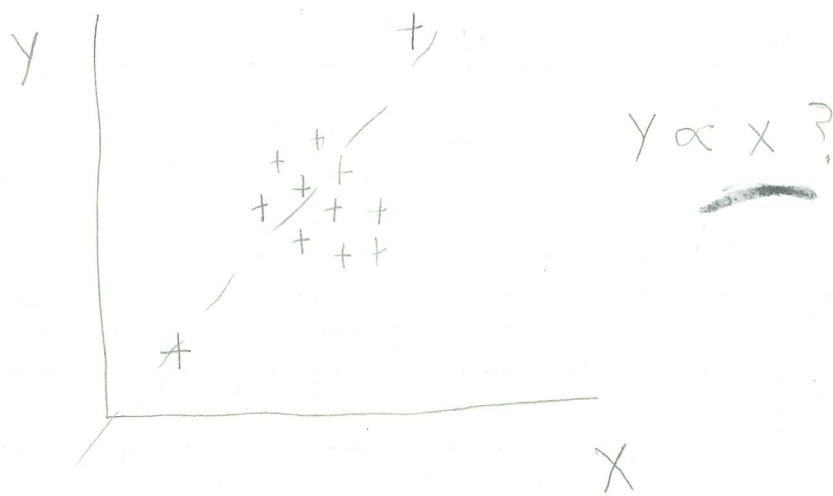
LINEAR CORRELATION COEFF. "r" IS DESIGNED FOR DATA  $(x, y)$  WITH ADDITIVE GAUSSIAN NOISE.

PERFECT WORLD:  $y' = mx' + b$

NOISE:  $y = y' + \varepsilon_1$ ,  $P(\varepsilon_1) \propto e^{-\varepsilon_1^2/2\sigma^2}$

$x = x' + \varepsilon_2$ , -- "

BUT "r" IS EASILY BROKEN BY A FEW "OUTLIERS": //



THIS HAPPENS MOST OFTEN WITH NOISE THAT HAS FAT TAILS, E.G.

$$P(\varepsilon) \propto \frac{1}{1+x^2}$$

r SIMPLY "WEIGHS" OUTLIERS TOO HEAVILY.

# NONPARAMETRIC CORRELATION STATISTICS (NR § 14.6)

GENERAL IDEA:

IF I SORT MY DATA  $(x, y)$  BY ASCENDING  $x$ ,  
HOW CLOSE IS THAT TO SORTING BY ASCENDING  $y$ ?

MOTIVATION:

MUCH LIKE THE MEDIAN, ALL THAT MATTERS IS RANK ORDER (NOT MAGNITUDE).  $\therefore$  INSENSITIVE TO OUTLIERS.

## SPEARMAN RANK-ORDER CORRELATION COEFF.

① REPLACE  $(x_i, y_i)$  WITH THEIR RANKS  $(R_i, S_i)$

② " $r_s$ " IS THE LINEAR CORRELATION COEFFICIENT USING  $(R, S)$  IN PLACE OF  $(x, y)$ :

$$r_s = \frac{\sum_{i=1}^N (R_i - \bar{R})(S_i - \bar{S})}{\sqrt{\sum_{i=1}^N (R_i - \bar{R})^2} \sqrt{\sum_{i=1}^N (S_i - \bar{S})^2}}$$

$-1 \leq r_s \leq 1$ .

(NOTE THAT  $\frac{N}{2} = \bar{R} = \bar{S}$ )

SPEARMAN IS FAST (LIMITED BY SORTING,  $N \log N$ )

NR ROUTINE `spear()` GIVEN  $(x_i, y_i)$  CALCULATES  $r_s$  AND SIGNIFICANCE.

## KENDALL'S TAU (MORE NONPARAMETRIC/ROBUST) Comp. INTENSIVE TWIN SPEARMAN)

- N DATA POINTS  $(x_i, y_i)$
- EXAMINE ALL PAIRS  $(x_i, y_i)$  vs.  $(x_j, y_j)$   
(THERE ARE  $\frac{1}{2}N(N-1)$  OF THEM!)  $\Rightarrow \Theta(N^2)$  COMPUTATIONS.
- CLASSIFY PAIRS AND COUNT HOW MANY ARE:
  - $N_c$ , CONCORDANT:  $(x_j - x_i)$  SAME SIGN AS  $(y_j - y_i)$
  - $N_D$ , DISCORDANT:  $(x_j - x_i)$  OPPOSITE SIGN AS  $(y_j - y_i)$
  - $N_x$ , EXTRA-X:  $x_i = x_j$  (BUT  $y_i \neq y_j$ )
  - $N_y$ , EXTRA-Y:  $y_i = y_j$  (BUT  $x_i \neq x_j$ )

$$\tau = \frac{N_c - N_D}{\sqrt{N_c + N_D + N_x} \cdot \sqrt{N_c + N_D + N_y}}$$

$-1 < \tau < 1$

UNDER NULL HYPOTHESIS OF NO ASSOCIATION  $X$  vs.  $Y$ ,  
 $\tau$  IS APPROX. NORMALLY DISTRIBUTED, WITH  $\bar{\tau} = 0$

AND

$$\sigma_{\tau} = \sqrt{\frac{4N+10}{9N(N-1)}} \rightarrow \sqrt{\frac{2}{3N}} \text{ FOR LARGE } N$$

NOTE:  $\tau$  CAN BE SPEED UP FOR BINNED DATA  
 (E.G. ORDINAL CONTINGENCY TABLE)

NR IMPLEMENTATIONS OF KENDALL's  $\tau$ :

kendall1() --- FOR 2D CONTINUOUS DATA  
GIVEN  $(x_i, y_i)$   
CALCULATES  $\tau$ , SIGNIFICANCE

kendall2() --- FOR 2D ORDINAL (BINNED) DATA  
GIVEN A TABLE  $T_{ij}$  OF COUNTS  
CALCULATES  $\tau$ , SIGNIFICANCE

BOTTOM LINE: ① FOR UNBINNED DATA  $(x_i, y_i)$ ,  
SPEARMAN IS FASTER. KENDALL OFFERS NO  
GREAT ADVANTAGE.

② FOR BINNED DATA,  $\tau$  IS QUICKER AND MORE  
NATURAL. (IF # BINS IS MUCH SMALLER THAN  
#DATA POINTS).

# A ROBUST ALTERNATIVE TO LINEAR LEAST SQUARES:

## APPLICATION:

PORTER & KLIMCHUK 1995 ApJ 454, 499  
OR

KLIMCHUK & PORTER 1995 NATURE 377, 131

FITTING  $y'_i = mx'_i + b$

WE MEASURE  $y_i = y'_i + \varepsilon_i$ ,  $x_i = x'_i$

GIVEN NO PRIOR KNOWLEDGE OF  $P(\varepsilon)$  [BUT ASSUME INDEPENDENT OF  $x, y$ ]  
 → EXCEPT WE ASSUME MEDIAN( $\varepsilon$ ) = 0.  
 (BUT YOU CAN BET  $P(\varepsilon)$  IS NO WUSSY GAUSSIAN!)

## APPROACH

OBVIOUSLY, WE EXPECT  $y_i$  CORRELATED WITH  $x_i$ . CONSIDER:

$$\textcircled{1} \quad y_i^* \equiv y_i - m^* x_i = b + \varepsilon_i + (m - m^*) x_i$$

$y^*$  WILL BE UNCORRELATED (IN FACT INDEPENDENT) OF  $x$

IF  $m^* = m$ . THUS,

$$\textcircled{2} \quad \text{MINIMIZE: } \bar{\epsilon}(x, y^*) \text{ W.R.T. } m^*.$$

(THE RESULT IS  $m^* \approx m$ )

$$\textcircled{3} \quad \text{LET } b^* = \text{MEDIAN}(y^*) \text{ --- ASSUMES MEDIAN}(\varepsilon_i) = 0.$$

ALTERNATIVELY, CONSIDER:

$$x_i = \frac{y'_i}{m} - \frac{b}{m} = \frac{1}{m}(y'_i - \varepsilon_i - b)$$

$$\text{LET } x_i^* \equiv x_i - \frac{1}{m^*} y'_i = \frac{1}{m}(\varepsilon_i + b) + \left(\frac{1}{m} - \frac{1}{m^*}\right) y'_i$$

CAN WE MINIMIZE  $\bar{\epsilon}(x^*, y)$  W.R.T.  $m^*$

AND GET THE SAME RESULT AS BEFORE?

NO: FOR  $m = m^*$ ,  $x_i^* = \frac{1}{m}(\varepsilon_i + b)$ .  $x^*$  IS

STILL CORRELATED WITH  $y$  BECAUSE  $\varepsilon$  IS CORRELATED WITH  $y'$ !  
 (THOUGH  $\varepsilon$  IS UNCORRELATED WITH  $y'$ !)

$$\textcircled{*} \quad \text{ASSUME } P(x', y', \varepsilon) = P(x', y)P(\varepsilon).$$

# NONPARAMETRIC (RANK) CORRELATION IS A

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SUBSET OF "ROBUST ESTIMATION" METHODS (NR § 15.7) \*

VERY BROAD FIELD, EXPLODED c. 1960, STILL UNDER RESEARCH!

OBJECTIVE	A TRADITIONAL APPROACH	ROBUST METHOD(S)
CENTRAL TENDENCY OF $\{x_i\}$	MEAN	MEDIAN
COMPARE 2 DISTRIBUTIONS	MOMENTS	KOLMOGOROV-SMIRNOV STATISTIC
CORRELATION	LINEAR COEFF. "r"	NONPARAMETRIC CORRELATION E.G. KENDALL'S $\tau$
FITTING TRENDS $y = mx + b$	LINEAR LEAST SQUARES	METHOD OF KLIMCHUK & PORTER; MIN ABS DEV
MULTI-PARAMETER FITTING $y(x)$	NONLINEAR LEAST SQUARES	LOESS NONPARAMETRIC REGRESSION; MIN ABS DEV
ESTIMATING CONFIDENCE LEVELS	INTEGRATE PDF OF SOME STATISTIC, ASSUMING GAUSSIAN ADDITIVE NOISE IN THE DATA	MONTE CARLO (E.G. BOOTSTRAP)* NR § 15.6

IN GENERAL --- ↑  
FASTER --- MORE RELIABLE  
 ↑  
 GREATER STATISTICAL  
 POWER (IF ALL  
 ASSUMPTIONS MET)  
 (FEWER ASSUMPTIONS)

\* SEE ALSO EFRON & TIBSHIRANI, SCIENCE 253, 390 (1991)

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## KOLMOGOROV-SMIRNOV TEST

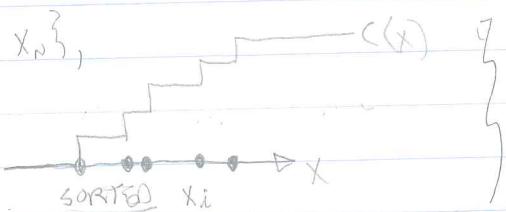
DEPENDS ON EVALUATING AND COMPARING  
CUMULATIVE DISTRIBUTION FUNCTIONS:

NOTATION FOR  
STANDARD  
CUMULATIVE DIST.

$$C(x) = \int_{-\infty}^x P(x') dx'$$

• WITH SAMPLED DATA  $\{x_1, \dots, x_N\}$ ,

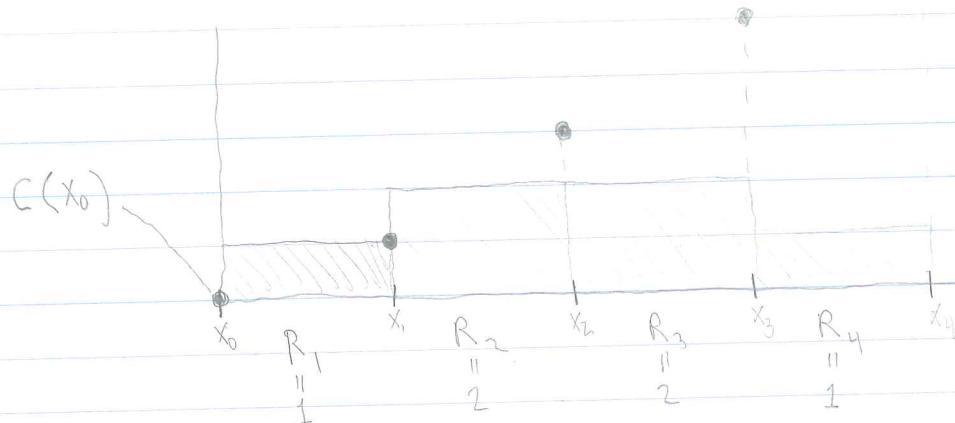
$$C(x) = \sum_{x_i \leq x} \frac{1}{N}$$



WE HAVE  
 $C(x)$  AT  
 $2N$  POINTS.

• WITH BINNED DATA, WE CAN ONLY EVALUATE  $C(x)$  ON  
THE BORDERS BETWEEN BINS:

$$C(x_4)$$



## THE K-S STATISTIC:

$$D = \max \left| C(x) - C(y) \right|$$

• INVARIANT UNDER REPARAMETERIZATION OF  $x$ :

$$x \rightarrow \log x, y \rightarrow \log y$$

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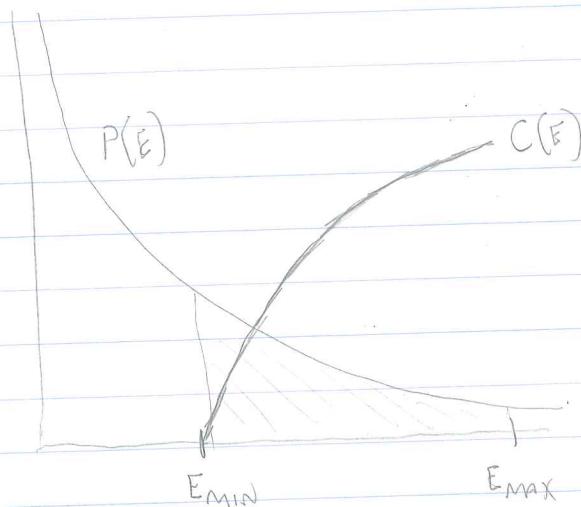
## NOTES ON K-S STATISTIC D:

- VERY SENSITIVE TO MEDIAN  $\bar{x}_m$ .
- CONTAINS AN INTRINSIC NOTION OF FUNCTION WIDTH AND SHAPE THAT DOES NOT DEPEND ON THE EXISTENCE OF MOMENTS OF  $P(x)$ .
- WORKS FOR ANY  $P(x)$  THAT CAN BE NORMALIZED  
I.E.  $\int_{-\infty}^{\infty} P(x) dx$  CONVERGES.
- CAN BE EXTENDED TO ANY  $P(x) > 0$  ON A RESTRICTED INTERVAL  $[a, b]$  AS LONG AS

$$\int_a^b P(x) dx \text{ CONVERGES.}$$

E.g. POWER LAW DISTRIBUTION OF FLARE ENERGIES:

$$P(E) = E^{-\alpha}$$



$$C(E) = \int_{E_{\min}}^E P(E') dE'$$

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NULL HYPOTHESIS:  $P(x) = P(y)$

K-S TEST:

$$\text{PROBABILITY } (D > \text{OBSERVED}) = Q_{KS} \left[ D \left( \sqrt{N_e} + 0.12 + \frac{0.11}{\sqrt{N_e}} \right) \right]$$

WHERE:  $Q_{KS}(\lambda) = 2 \sum_{j=1}^{\infty} (-1)^{j-1} e^{-2j^2 \lambda^2}$  FOR  $N_e \gg 1$

$$(Q_{KS}(0) = 1, Q_{KS}(\infty) = 0)$$

→ PLOT THIS!

AND:

$$N_e \equiv \begin{cases} N & \text{IF COMPARING } \{x_1, \dots, x_N\} \text{ TO } P(x) \\ \frac{N_1 N_2}{N_1 + N_2} & \text{IF COMPARING } \{x_1, \dots, x_N\} \text{ TO } \{y_1, \dots, y_N\} \end{cases}$$

"EFFECTIVE NUMBER OF DATA POINTS"

FOR SMALL  $N_e$ , OR BINNED DATA,  $Q_{KS}$  MAY DIFFER.

POSSIBLE APPROACHES:

- DERIVE MORE GENERAL  $Q_{KS}$  ANALYTICALLY

- RUN A MONTE-CARLO TEST TO ESTIMATE STATISTICAL SIGNIFICANCE OF  $D$ .