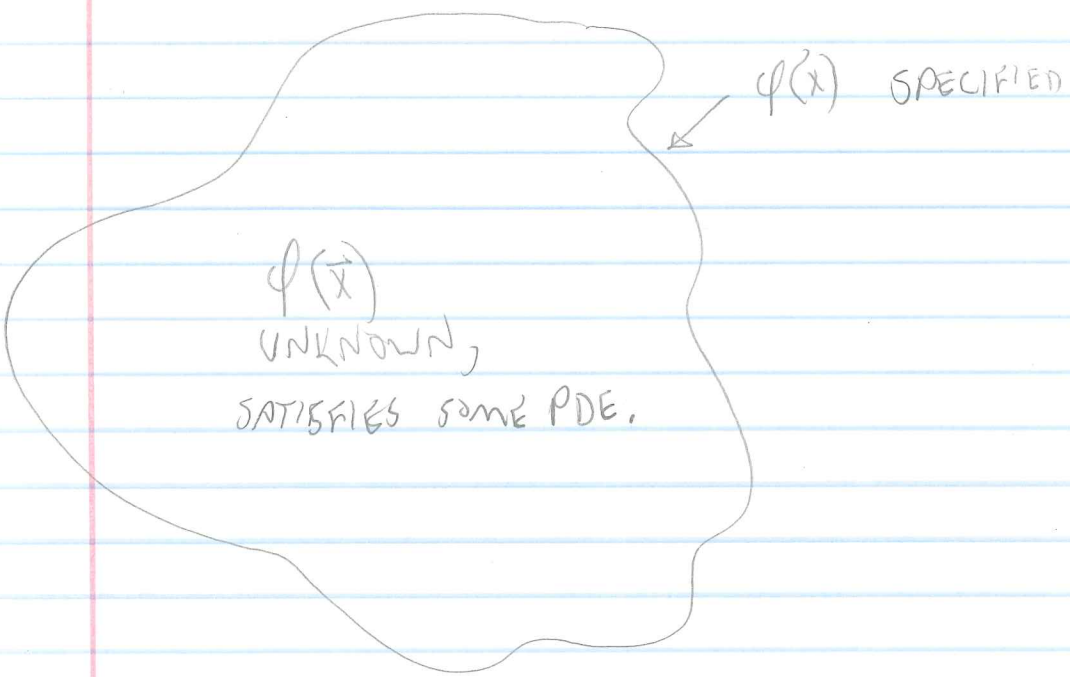


P, D, E. S

BOUNDARY VALUE PROBLEMS



CLASSIC EXAMPLE IS POISSON'S EQUATION:

$$\nabla^2 \phi = \rho(\vec{x}), \text{ i.e. } \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \phi = \rho$$

ELLIPTIC
EQN.

THESE PROBLEMS ARE TYPICALLY SOLVED ON A GRID,
E.G.

$$X_i = i \Delta, \quad Y_i = i \Delta, \quad Z_i = i \Delta$$

~~$$\frac{\partial \phi}{\partial x} = \frac{\phi(x+s) - \phi(x-s)}{2s}$$~~

~~$$\frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial x} \right) = \frac{\phi(x+2s) - 2\phi(x) + \phi(x-2s)}{(2s)^2}$$~~

~~LET $s = \Delta/2$~~

$$\left. \frac{\partial^2 \phi}{\partial x^2} \right|_{x_i} = \frac{\phi(x_{i+1}) - 2\phi(x_i) + \phi(x_{i-1}))}{\Delta^2}$$

SKIP?

TAYLOR SERIES:

$$\begin{aligned} \varphi(x_{i\pm 1}) = \varphi(x_i) &\pm \Delta \left. \frac{\partial \varphi}{\partial x} \right|_i + \frac{1}{2} \Delta^2 \left. \frac{\partial^2 \varphi}{\partial x^2} \right|_i \\ &\pm \frac{1}{6} \Delta^3 \left. \frac{\partial^3 \varphi}{\partial x^3} \right|_i + \frac{1}{24} \Delta^4 \left. \frac{\partial^4 \varphi}{\partial x^4} \right|_i \pm \dots \end{aligned}$$

$$\left. \frac{\partial^2 \varphi}{\partial x^2} \right|_i = \frac{\varphi(x_{i+1}) - 2\varphi(x_i) + \varphi(x_{i-1}))}{\Delta^2} + \frac{1}{12} \Delta^2 \left. \frac{\partial^4 \varphi}{\partial x^4} \right|_i + \dots$$

TRUNCATION ERROR

SUPPOSE WE HAVE POISSON'S EQN.,

$$\nabla^2 \varphi(x, y) = \rho(x, y),$$

$$\nabla^2 \varphi_{ij} = \rho_{ij}$$

$$\frac{(4\varphi_{ij} - \varphi_{i+1,j} - \varphi_{i-1,j} - \varphi_{i,j+1} - \varphi_{i,j-1})}{\Delta^2} = \rho_{ij}$$

$$\varphi_{ij} = \left(\frac{\varphi_{i+1,j} + \varphi_{i-1,j} + \varphi_{i,j+1} + \varphi_{i,j-1}}{4} \right) + \frac{\Delta^2}{4} \rho_{ij}$$

"ALL" WE NEED TO DO IS MAKE THIS TRUE FOR EVERY i, j INSIDE THE BOUNDARY!

HOW?

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FOR AN ODE, E.G.

$$\frac{d^2 \psi}{dx^2} = \rho(x)$$

WE MIGHT SOLVE THE BOUNDARY VALUE PROBLEM BY SHOOTING.

BUT FOR PDES, SHOOTING IS NOT AN OPTION BECAUSE THERE ARE 2 OR MORE INDEPENDENT VARIABLES (E.G. x, y, z).

WE THEREFORE SOLVE THE BOUNDARY VALUE PROBLEM BY RELAXATION.

E.G. $\nabla^2 \psi = 0$, START WITH INITIAL GUESS ψ^0 ;

CONSTRUCT AN INITIAL VALUE PROBLEM:

$$\frac{\partial \psi}{\partial t} = k \nabla^2 \psi$$

TAKE LIMIT $t \rightarrow \infty$

$$\frac{\partial \psi}{\partial t} \rightarrow 0$$

$$k \nabla^2 \psi \rightarrow 0$$

FTCS:

$$\psi^{n+1} = \psi^n + \delta K \nabla^2 \psi^n$$

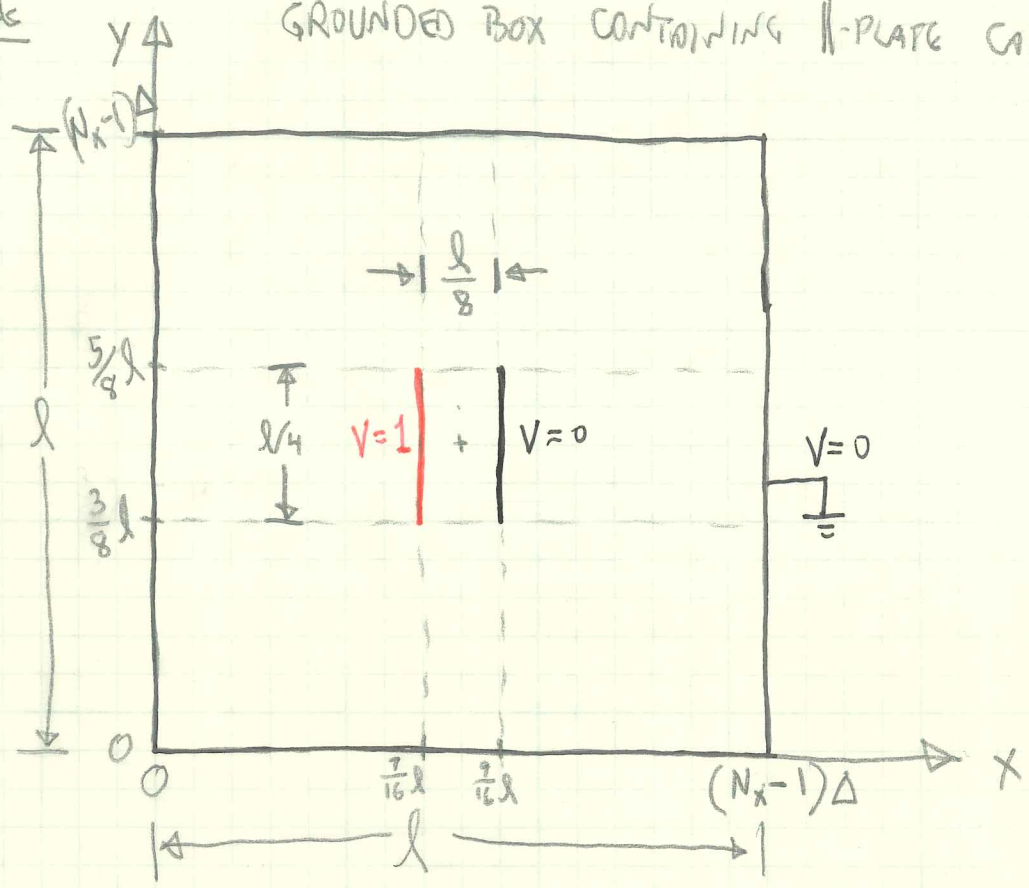
$$\psi_{ij}^{n+1} = \psi_{ij}^n + \frac{\delta K}{\Delta^2} (\psi_{i+1,j} + \psi_{i-1,j} + \psi_{i,j+1} + \psi_{i,j-1} - 4\psi_{ij})$$

E.G. CHOOSE $\frac{\delta K}{\Delta^2} = \frac{1}{4}$

"POINT RELAXATION"

EXAMPLE

GROUNDING BOX CONTAINING ||-PLATE CAP.



GRID SPACING Δ

$$l = (N_x - 1)\Delta$$

$$\text{CAPACITOR TOP} = \frac{5}{8}l = \frac{5}{8}(N_x - 1)\Delta$$

$$\text{CAPACITOR BOTTOM} = \frac{3}{8}l = \frac{3}{8}(N_x - 1)\Delta$$

$$\text{" LEFT} = \frac{7}{16}l = \frac{7}{16}(N_x - 1)\Delta$$

$$\text{RIGHT} = \frac{9}{16}l = \frac{9}{16}(N_x - 1)\Delta$$

IN OUR EXAMPLE, I LET $N_x = 65$
(SO $N_x - 1$ DIVISIBLE BY 16).

SOLUTION STRATEGY:

- ELLIPTICAL BV PROB \rightarrow PARABOLIC INIT VAL PROBLEM
- TIMESTEP: LOBOTOMIZED VERSION OF ALTERNATING DIRECTION IMPLICIT.
- RAMP TIMESTEP LARGE \rightarrow SMALL

22-141 50 SHEETS
 22-142 100 SHEETS
 22-144 200 SHEETS



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capacitor.c

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```

#include <stdio.h>
#include <math.h>

#include "/usr/local/src/recipes_c-ansi/include/nr.h"
#include "/usr/local/src/recipes_c-ansi/include/nrutil.h"
// #include "/usr/local/src/recipes_c-ansi/recipes/tridag.c"

void implicit(float t, float q[], short f[], long nq, float delta_t);
void A_1(float t, float delta, float q[], short f[], float a[], float b[], float
c[]);
void bc(float psi[][], short flag[][]);

#define KAPPA 1.0
#define NX 65 //NX-1 should be divisible by 16.
#define DX 1.0
#define NT 2000 //number of relaxation time steps
#define DT 1000.0 //this is the initial time interval.

int main(void)
{
    float psi[NX][NX], q[NX], delta_t;
    short flag[NX][NX], f[NX];
    long i, j, k;
    FILE *outfile;

    // Initialize/set boundary conditions on psi[][] and
    // mark boundary locations in flag[][]
    bc(psi, flag);

    // Relax NT "time" steps
    for (k=1; k<=NT; k++) {

        // Time step delta_t ramps down from DT to 1.0; → WHY?
        delta_t = DT-(float)k;
        if (delta_t < 1.0) delta_t=1.0;

        // do the rows
        for (i=1; i<NX-1; i++) {
            implicit(0.0, psi[i], flag[i], NX, delta_t);
        }

        // do the columns
        for (i=1; i<NX-1; i++) {
            for (j=1; j<NX-1; j++) {
                q[j] = psi[j][i];
                f[j] = flag[j][i];
            }
            implicit(0.0, q, f, NX, delta_t);
            for (j=1; j<NX-1; j++) {
                psi[j][i] = q[j];
            }
        }
    }

    // Save results
    outfile=fopen("data.txt", "w");
    for(i=0; i<NX; i++) {
        for(j=0; j<NX; j++) fprintf(outfile, "%f", psi[i][j]);
        fprintf(outfile, "\n");
    }
}

void implicit(float t, float q[], short flag[], long nq, float delta_t)
{

```

NOTE:
BC'S HANDLED
BY implicit()

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capacitor.c

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```

float a[NX], b[NX], c[NX], q1[NX];
long i;

A_1(t, delta_t, q, flag, a, b, c); //get the tridiagonal propagator matrix
tridag(a-1, b-1, c-1, q-1, q1-1, NX);
for(i=0; i<NX; i++) q[i] = q1[i];
}

// Propagator for the parabolic initial value problem, FTCS scheme.
// This is used to implement the implicit time step.
void A_1(float t, float delta, float q[], short flag[], float a[], float b[], float c[])
{
    long i;
    float foo;

    foo = delta*KAPPA/(DX*DX);

    for (i=0; i<NX; i++) {
        if (flag[i] == 1) { // this cell is a fixed boundary value
            a[i] = 0.0; //lower diagonal
            b[i] = 1.0; //main diagonal
            c[i] = 0.0; //upper diagonal
        } else {
            a[i] = -foo; //lower diagonal
            b[i] = (1. + 2.*foo); //main diagonal
            c[i] = -foo; //upper diagonal
        }
    }
}

void bc(float psi[NX][NX], short flag[NX][NX])
{
    long i, j, top, bottom, left, right;
    FILE *dfile;

    //first, zero the interior
    for (i=0; i<NX; i++) {
        for (j=0; j<NX; j++) {
            psi[i][j]=0.0; //zero computational domain interior
            flag[i][j]=0; //clear boundary flag
        }
    }

    // NOW IMPLEMENT VALUES FOR DIRICHLET (FIXED) BOUNDARIES
    //edges
    for (i=0; i<NX; i++) {
        psi[0][i]=0.0;
        psi[i][0]=0.0;
        psi[NX-1][i]=0.0;
        psi[i][NX-1]=0.0;

        flag[0][i]=1;
        flag[i][0]=1;
        flag[NX-1][i]=1;
        flag[i][NX-1]=1;
    }

    //capacitor plates
    top = (NX-1)*5/8;
    bottom = (NX-1)*3/8;
    left = (NX-1)*7/16;
    right = (NX-1)*9/16;
}

```


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capacitor.c

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```
//Save a little data file with plate dimensions:
dfile=fopen("plates.txt", "w");
fprintf(dfile, "%d %d\n", top, left);
fprintf(dfile, "%d %d\n", bottom, left);
fprintf(dfile, "\n");
fprintf(dfile, "%d %d\n", top, right);
fprintf(dfile, "%d %d\n", bottom, right);
fprintf(dfile, "\n");
fclose(dfile);

for (i=bottom; i<=top; i++) {
    psi[left ][i] = 1.0;
    psi[right][i] = 0.0;

    flag[left ][i] = 1;
    flag[right][i] = 1;
}
}
```

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