Inversion of MOSES Data

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The Multi-Order Solar Extreme Ultraviolet Spectrograph (MOSES) is a snapshot imaging spectrometer payload planned for launch from White Sands Missile Range in July, 2005. We describe the Smooth Multiplicative Algebraic Reconstruction Technique (SMART), a new algorithm for near real time reconstruction of line profile parameters from MOSES data. Though the technique was developed for generating a quick look data product, the results have high fidelity. In simulations, doppler shifts are reconstructed with < 0.25 pixel accuracy (RMS).









Motivation



MOSES Allows us to take spectra simultaneously over a large field. Because there is no slit, the exposure can be very short. Since the MOSES field of view is 2048×1024 pixels, this amounts to a 1000-fold speed advantage over a slit spectrograph of comparable aperture and resolution.

Disentangling spatial and spectral information Can we turn the four projections $I_+(x + \lambda)$, $I_0(x)$, $I_-(x - \lambda)$ and $I_{\infty}(\lambda)$ back into $I(x, \lambda)$? And if so, how?





Algebraic Reconstruction Technique

Smooth Multiplicative

1. $G(x,\lambda) = I_0(x) I_\infty(\lambda)/N$ Initial guess. 2. $[I'_0, I'_+, I'_-, I'_\infty] = TG$ Projection. 3. $G = G \left[\frac{I_0(x)}{I'_0(x)} \right]^{\gamma} \cdot \left[\frac{I_+(x+\lambda)}{I'_+(x+\lambda)} \right]^{\gamma} \cdot \left[\frac{I_-(x-\lambda)}{I'_-(x-\lambda)} \right]^{\gamma} \cdot \left[\frac{I_\infty(\lambda)}{I'_\infty(\lambda)} \right]^{\gamma}$ Correction. 4. $G = G \otimes \frac{1}{1+2a+2b} \begin{bmatrix} 0 & a & 0 \\ b & 1 & b \\ 0 & a & 0 \end{bmatrix}$ Smoothing. 5. $[I'_0, I'_+, I'_-, I'_\infty] = \overline{T}G$ Projection. 6. Evaluate goodness of fit, χ_0^2 , χ_+^2 , χ_-^2 .

7. Adjust smoothing parameters, $a = a/(\chi_+^2 \chi_-^2)$; $b = b/\chi_0^2$. 8. Loop to (3).





We used a single SUMER raster containing O III λ 703.87 and Mg IX λ 706.02 as our "true" Sun. These lines resemble the He II λ 303.8 and Si XI λ 303.3 that will be observed by *MOSES*. The data cube was rescaled to 300 counts per (x, y)pixel.

- 1. Velocities were measured by centroiding the SUMER O III line.
- 2. Added shot noise and re-measured the line centers.
- 3. Projection of MOSES orders m = -1, 0, +1 plus noise.
- 4. Reconstructed data cube using SMART.
- 5. Measured velocities from the reconstructed spectra.



SMART example





True velocity (SUMER data)



Data resampled with shot noise (0.12 pixel RMS)



Reconstruction from *MOSES* projections (0.20 pixel RMS)







RMS error 0.12 pixels. This represents reponse of an idealized slit spectrograph. $^{\rm 8}$



Velocity scatter (reconstruction)





RMS error 0.20 pixels. Reconstruction from multi-order data systematically underestimates velocity.



Line separation



It is challenging to isolate the coronal line, which is nearly an order of magnitude weaker than the TR line.



The recovered coronal image is distinctly recognizable, though some of the transition region fine structure "shows through".



Algorithm Speed



Approximate time for inversion of a 280×1 pixel FOV (on a slow laptop).

Algorithm	Time
Simulated annealing	10 hr
Fourier	2 min
SMART	1 sec







- Problems solved:
 - Speed: SMART converges in 15 iterations. Inversion of ($\sim 1\,{\rm GB})$ MOSES data in 1 day.
 - Regularization. Global $\chi^2_R = 1$.
 - Sub-pixel (~ 0.2 pixel RMS) velocity measurement in HeII.
 - Separation of weak coronal line (Si XI).
- Remaining issues:
 - Velocities are systematically underestimated.
 - Bright pixels are underfitted, dim pixels are overfitted. Probably because my χ^2_R has the wrong form for dim pixels.
 - $I_{\infty}(\lambda)$: How to infer integrated line ratios?



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